GAMME ROBOTS LUCAS

AL | Axe Linéaire

ALS | Axe Linéaire au Sol

ALSS | Axe Linéaire au Sol Standard

ALSS-1R

ALSS-2R

ALSS-1C

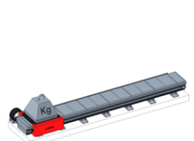
ALSS-2C

ALSP | Axe Linéaire au Sol Protégé

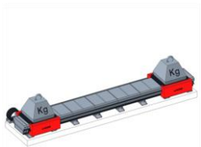
ALSP-1R

ALSP-2R

ALSP-1C



ALSP-2C



ALE | ALC | ALI | Axe Linéaire sur Poteaux

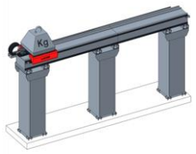
ALE | Axe Linéaire Élevé

ALES | Axe Linéaire Élevé Standard

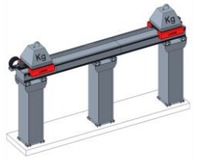
ALES-1R

ALES-2R

ALES-1C



ALES-2C

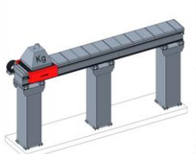


ALEP | Axe Linéaire Élevé Protégé

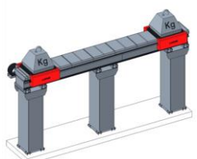
ALEP-1R

ALEP-2R

ALEP-1C

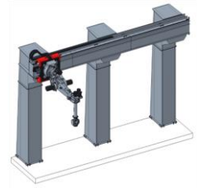


ALEP-2C

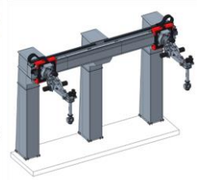


ALCS | Axe Linéaire sur Chant Standard

ALCS-1R

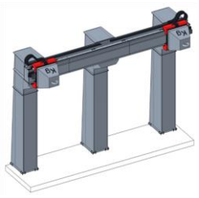


ALCS-2R



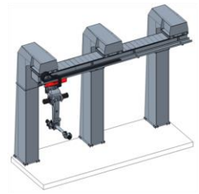
ALCS-1C

ALCS-2C

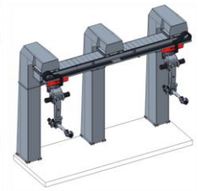


ALIS | Axe Linéaire Inversé Standard

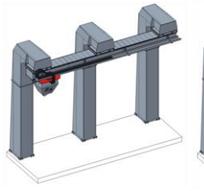
ALIS-1R



ALIS-2R



ALIS-1C



ALIS-2C

Légende : AL | Axe Linéaire

AL — S — S — - — 1R

- AL : Famille de robot
- S : Position de l'axe
- S : Protection de l'axe
- 1R : Élément(s) à déplacer

ALSS-1R : Axe Linéaire au Sol Standard pour 1 Robot
ALSP-2R : Axe Linéaire au Sol Protégé pour 2 Robots
ALES-1C : Axe Linéaire Élevé Standard pour 1 Charge
ALEP-2C : Axe Linéaire Élevé Protégé pour 2 Charges

GAMME ROBOTS LUCAS

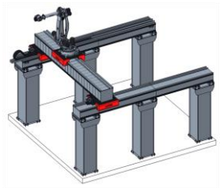
RC | Robot Cartésien

RC2 | Robot Cartésien 2 axes

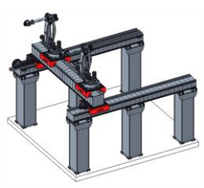
RC2-XY | Robot Cartésien 2 axes XY

RC2-XYE | Robot Cartésien 2 axes XY Élevé

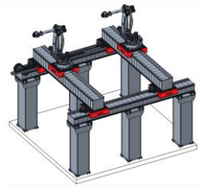
RC2-XYE-1Y1R



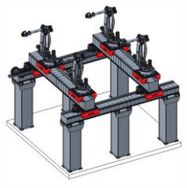
RC2-XYE-1Y2R



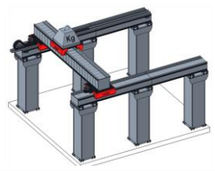
RC2-XYE-2Y2R



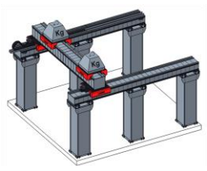
RC2-XYE-2Y4R



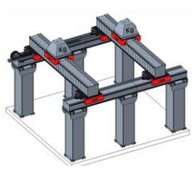
RC2-XYE-1Y1C



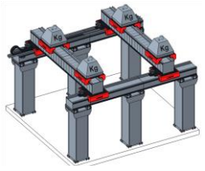
RC2-XYE-1Y2C



RC2-XYE-2Y2C

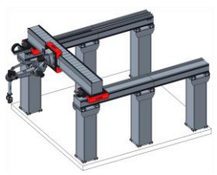


RC2-XYE-2Y4C

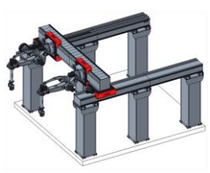


RC2-XYC | Robot Cartésien 2 axes XY sur Chant

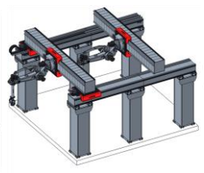
RC2-XYC-1Y1R



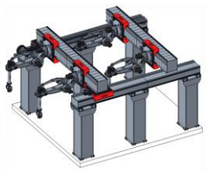
RC2-XYC-1Y2R



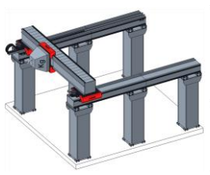
RC2-XYC-2Y2R



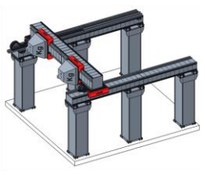
RC2-XYC-2Y4R



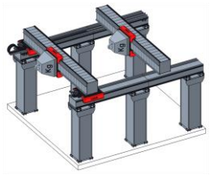
RC2-XYC-1Y1C



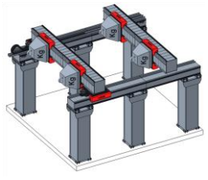
RC2-XYC-1Y2C



RC2-XYC-2Y2C

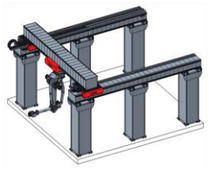


RC2-XYC-2Y4C

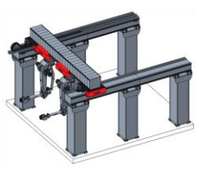


RC2-XYI | Robot Cartésien 2 axes XY Inversé

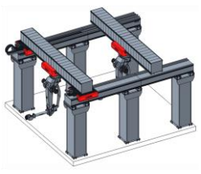
RC2-XYI-1Y1R



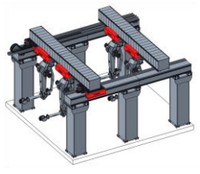
RC2-XYI-1Y2R



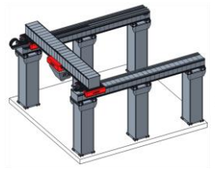
RC2-XYI-2Y2R



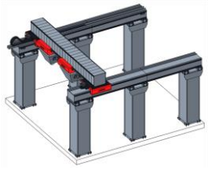
RC2-XYI-2Y4R



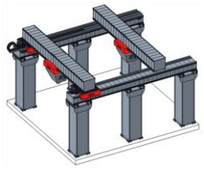
RC2-XYI-1Y1C



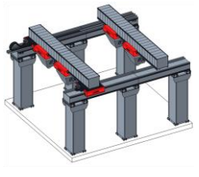
RC2-XYI-1Y2C



RC2-XYI-2Y2C

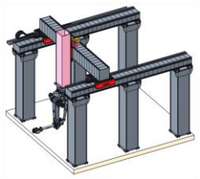


RC2-XYI-2Y4C

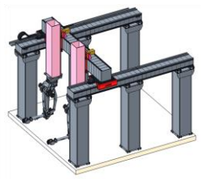


RC2-XZ | Robot Cartésien 2 axes XZ

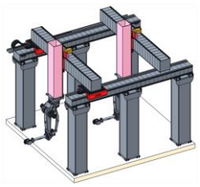
RC2-XZ-1Y1R



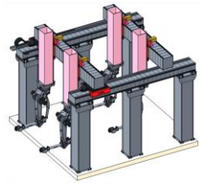
RC2-XZ-1Y2R



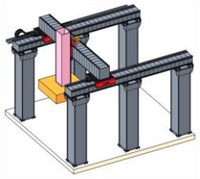
RC2-XZ-2Y2R



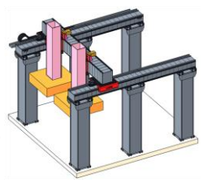
RC2-XZ-2Y4R



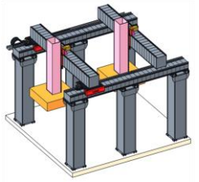
RC2-XZ-1Y1C



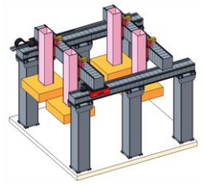
RC2-XZ-1Y2C



RC2-XZ-2Y2C

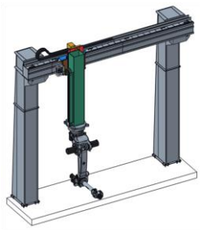


RC2-XZ-2Y4C

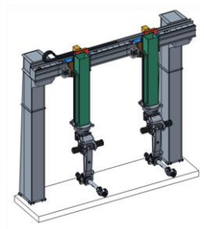


RC2-YZ | Robot Cartésien 2 axes YZ

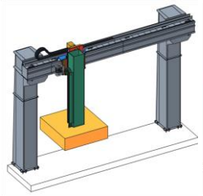
RC2-YZ-1R



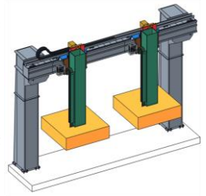
RC2-YZ-2R



RC2-YZ-1C

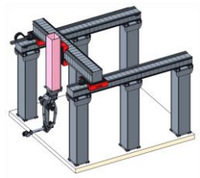


RC2-YZ-2C

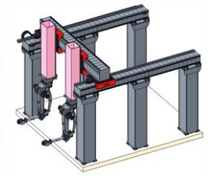


RC3 | Robot Cartésien 3 axes

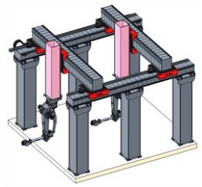
RC3-1Y1R



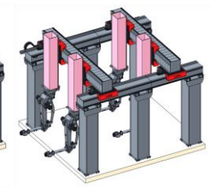
RC3-1Y2R



RC3-2Y2R



RC3-2Y4R



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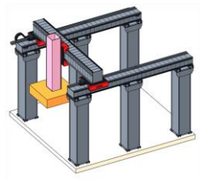

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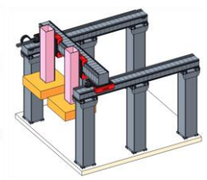
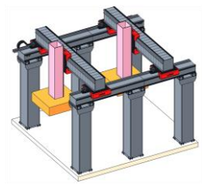
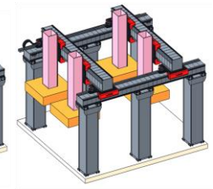


RC3-2Y2C



RC3-2Y4C



Légende : RC | Robot Cartésien

RC — Famille de robot

2 — Nombre de mobilité

XY — Axes mobiles

E — Orientation de l’axe Y

2Y — Nombre de poutre Y

4R — Élément(s) à déplacer

RC2-XYE-1Y1R : Robot Cartésien 2 axes XY avec 1 poutre Y en position Élevé pour déplacer 1 Robot
RC2-XYI-2Y4R : Robot Cartésien 2 axes XY avec 2 poutres Y en position Inversé pour déplacer 4 Robots
RC2-XZ-2Y2C : Robot Cartésien 2 axes XZ avec 2 poutres Y pour déplacer 2 Charges
RC2-YZ-1C : Robot Cartésien 2 axes YZ pour déplacer 1 Charge
RC3-2Y4C : Robot Cartésien 3 axes avec 2 poutres Y pour déplacer 4 Charges

GAMME ROBOTS LUCAS

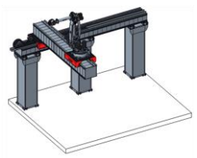
RCC | Robot Cartésien Cantilever

RCC2 | Robot Cartésien Cantilever 2 axes

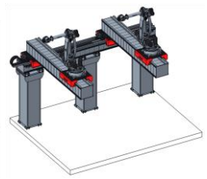
RCC2-XY | Robot Cartésien Cantilever 2 axes XY

RCC2-XYE | Robot Cartésien Cantilever 2 axes XY Élevé

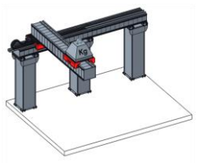
RCC2-XYE-1R



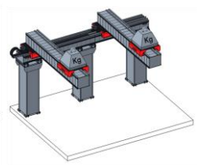
RCC2-XYE-2R



RCC2-XYE-1C

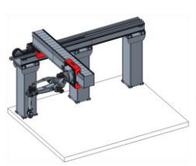


RCC2-XYE-2C

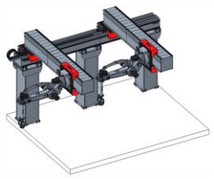


RCC2-XYC | Robot Cartésien Cantilever 2 axes XY sur Chant

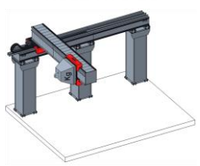
RCC2-XYC-1R



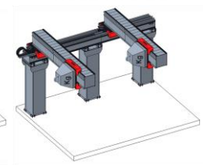
RCC2-XYC-2R



RCC2-XYC-1C

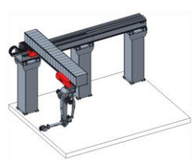


RCC2-XYC-2C

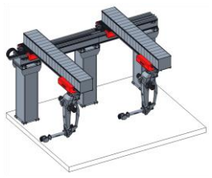


RCC2-XYI | Robot Cartésien Cantilever 2 axes XY Inversé

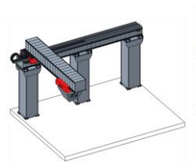
RCC2-XYI-1R



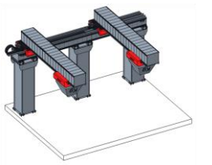
RCC2-XYI-2R



RCC2-XYI-1C

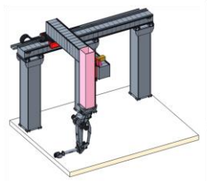


RCC2-XYI-2C

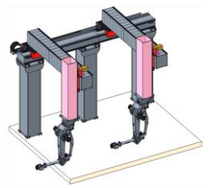


RCC2-XZ | Robot Cartésien Cantilever 2 axes XZ

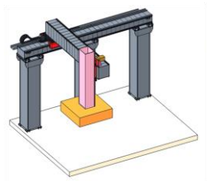
RCC2-XZ-1R



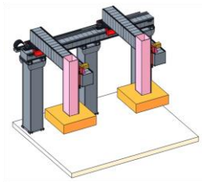
RCC2-XZ-2R



RCC2-XZ-1C

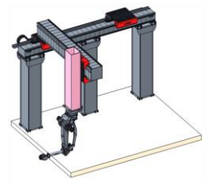


RCC2-XZ-2C

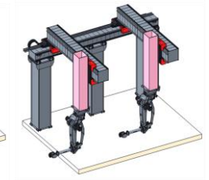


RCC3 | Robot Cartésien Cantilever 3 axes

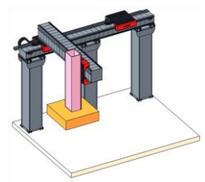
RCC3-1R



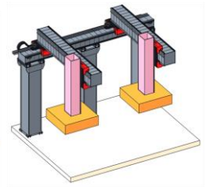
RCC3-2R



RCC3-1C



RCC3-2C



Légende : RCC | Robot Cartésien Cantilever

RCC — 2 — XY — E — 4R

- RCC : Famille de robot
- 2 : Nombre de mobilité
- XY : Axes mobiles
- E : Orientation de l'axe Y
- 4R : Élément(s) à déplacer

RCC2-XYE-1R : Robot Cartésien Cantilever 2 axes XY avec la poutre Y en position Élevé pour déplacer 1 Robot
RCC2-XYI-2R : Robot Cartésien Cantilever 2 axes XY avec la poutre Y en position Inversé pour déplacer 2 Robots
RCC2-XZ-2C : Robot Cartésien Cantilever 2 axes XZ pour déplacer 2 Charges
RCC3-1C : Robot Cartésien Cantilever 3 axes pour déplacer 1 Charge